

# TORQUEMASTER

## BRUSHLESS SERVO MOTORS

### **3000 SERIES**

#### **Performance Benefits**

MTI-Torque Systems specializes in the design of high performance brushless servo motors that provide efficiency, flexibility of application, and a long and trouble-free service life. Our TORQUEMASTER® 3000 series is no exception.

With fast response, accurate control and high torque-to-inertia ratios, you can count on the TORQUEMASTER 3000 Series of brushless servo motors to provide smooth operation throughout a full speed range. The 3000 Series delivers smooth and superior low speed performance, and maximum power ratings with low thermal resistance for high speed performance. In addition, with maximum torque in a smaller package, you can count on better pricing for a better overall value.

When integrated with high performance brushless amplifiers, TORQUE-MASTER 3000 Series brushless servo motors provide effective and highly efficient motion control solutions for a wide range of applications—including factory automation, packaging, robotics, machine tools, medical instrumentation and more.

#### **Design Features**

TORQUEMASTER BNR 3000 Series servo motors are rated from 12 lb.-in. to 34 lb.-in. with speeds and torque stability up to 10,000 RPM—accommodating DC bus voltages up to 325 volts. They utilize the latest in high performance Neodymium, permanent magnet technology, and are available in several standard windings (as well as custom windings) to meet your most demanding applications.

Each servo motor in the TORQUE-MASTER 3000 Series is ruggedly designed and manufactured for reliable performance. To satisfy many different applications, TORQUEMASTER 3000 Series motors are manufactured to NEMA/IEC specifications. For severe duty environments, the BNR design is also available with IP65 sealing.

TORQUEMASTER BNR 3000 Series servo motors come standard with a hall sensor or resolver commutation. Encoders, brakes, gearheads and other options are available.

#### **Series 3000, 325 VDC brushless servo motor — provides fast response, accurate control and high torque-to-inertia ratios**

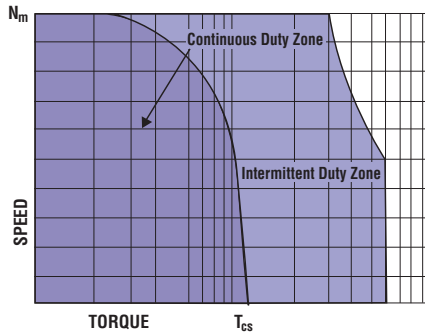
- 8 pole brushless design
- Continuous torque ratings up to 34 lb.-in.—with speeds up to 10,000 RPM
- IP65 Sealing available
- NEMA 23 mounting features standard
- IEC 72 Metric specifications available
- Maximum torque per frame size with high performance Neodymium magnets
- Superior low speed performance
- Numerous custom options available



# BRUSHLESS SERVO MOTOR CHARACTERISTICS

SYMBOL	MOTOR PARAMETER	UNITS	BNR3012A	BNR3024D	BNR3034E
$N_m$	Max Operating Speed	RPM	10,000	7000	5800
$T_c$	Max Stall Torque	lb.-in.(Nm)	12 (1.4)	24 (2.7)	34 (3.8)
$T_{pk}$	Peak Torque	lb.-in.(Nm)	60 (6.78)	110 (12.4)	150 (16.95)
$K_T$	Torque Sensitivity	lb.-in./AMP(Nm/Amp)	1.69 (.19)	4.22 (.47)	5.07 (.57)
$K_e$	Back E.M.F.	Volts/Krpm	20	50	60
$R_a$	Resistance Line to Line	Ohms	1.24	2.6	2.1
$L$	Inductance Line to Line	Millihenry	2	5.1	4.7
$J_m$	Rotor Inertia	lb.-in.-sec <sup>2</sup> (Kg-m <sup>2</sup> )	0.0008 (0.00009)	0.0015 (0.00017)	0.00196 (0.0011)
$T_F$	Static Friction	lb.-in.(Nm)	0.10 (.011)	0.10 (.011)	.125 (.014)
$F_i$	Viscous Friction	Lb-In/Krpm	.075	0.094	0.156
$R_{th}$	Thermal Resistance	Deg C/Watt	1.2	0.92	0.8
$T_m$	Mechanical Time Const.	Millisec.	3.2	1.98	1.41
$T_e$	Electrical Time Const.	Millisec.	1.5	2.0	3.6
$W_T$	Motor Weight	Lbs(Kg)	6 (2.71)	8 (3.62)	9.5 (4.30)

## TORQUE PERFORMANCE CURVES



NOTE: Continuous torque specifications obtained with motor mounted to an 8.5"x12"x 0.25" aluminum plate at 25°C ambient. Typical values are within ±10% of rating.

### Relationship Between $K_e$ & $K_T$

Torque Systems uses the following important motor performance parameters for the 3 phase square wave and 3 phase sine wave brushless motors in order to properly account for the British Imperial unit system currently used in the US.

$$K_e = \text{Line-to-line volts-peak} / \text{Krpm}^*$$

$$K_T = \text{Pound-inches (lb-in)} / \text{peak phase amps}$$

$K_e$  is related to  $K_T$  as follows:

$$K_T = K_e / 11.834 \text{ for 3 phase square wave current driven amplifiers}$$

$$K_T = K_e / 13.662 \text{ for 3 phase sinusoidal wave current driven amplifiers}$$

$$*\text{Krpm} = 1000 \text{ rpm}$$

For "RMS" values, divide peak values by  $\sqrt{2}$

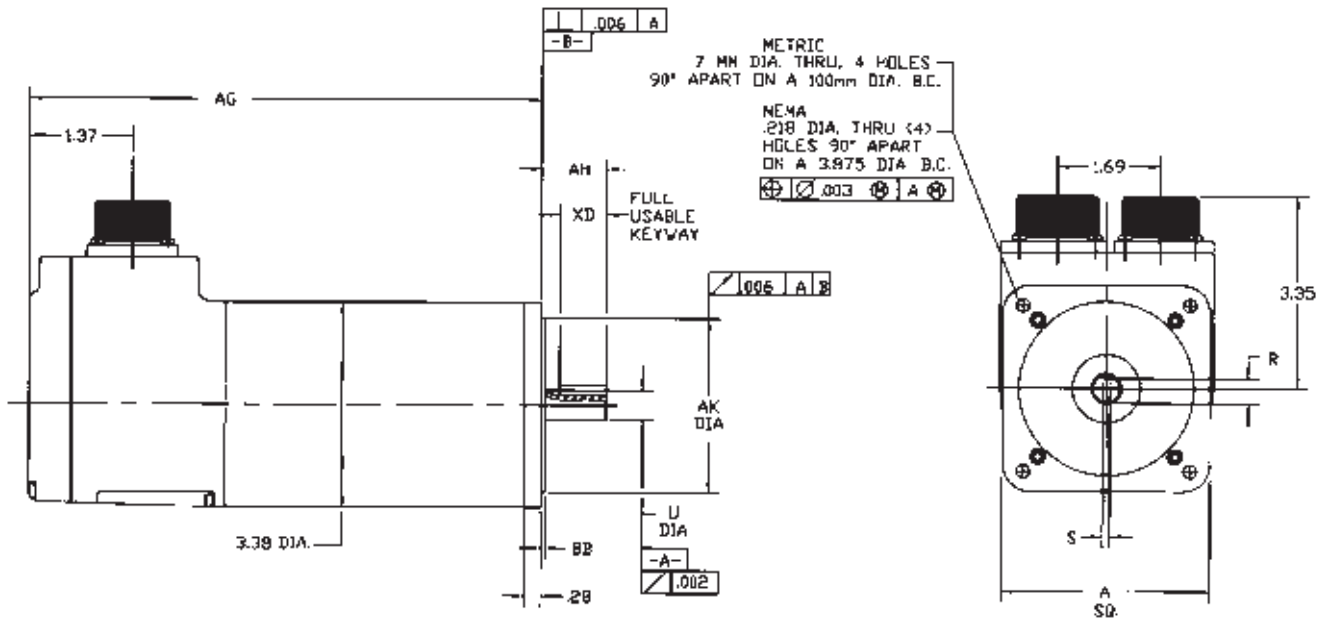
### STANDARD SPEED/TORQUE CURVE DATA FOR SIZING A SERVO MOTOR

$N_m$  = Maximum speed, continuous operation

$T_{cs}$  = Continuous stall torque

All specifications subject to change without notice.

# MECHANICAL SPECIFICATIONS\*



## DIMENSION CHART\* (Dimensions may change depending upon options)

PART NUMBER	AG	A	AK	BB	U		AH		XD	S	R
					STD	NEMA 34	STD	NEMA 34			
BNR3012	6.40	3.42	2.875	.06	.500	.375	1.00	1.19	.62	.125	.420/.413
BNR3024	7.40	3.42	2.875	.06	.500	.375	1.00	1.19	.62	.125	.420/.413
BNR3034	8.40	3.42	2.875	.06	.500	.375	1.00	1.19	.62	.125	.420/.413

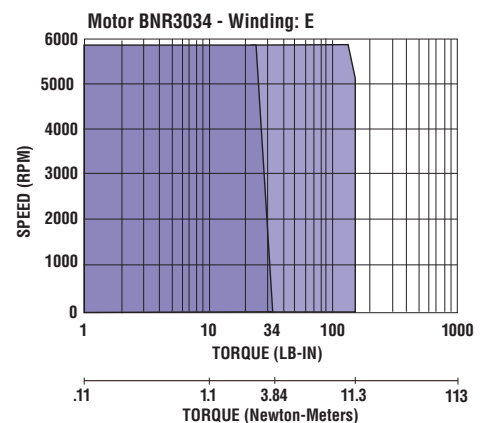
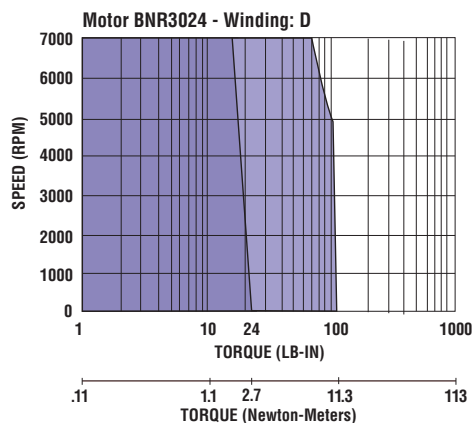
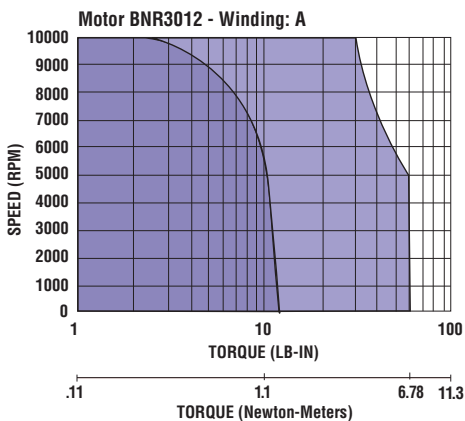
All dimensions meet NEMA 34 specifications except where indicated as standard.

### Metric IEC 72 (mm)

BNR3012	162.6	86.9	60j6	2.5	15j6	30	23	5.0	12
BNR3024	187.9	86.9	60j6	2.5	15j6	30	23	5.0	12
BNR3034	213.4	86.9	60j6	2.5	15j6	30	23	5.0	12

NOTE: Dimension AG includes commutation feedback device and/or a secondary feedback device as shown on ordering information.  
With internal brake option add 2.0" to dimension "AG"

## TORQUE PERFORMANCE CURVES



TORQUE SPEED CURVES OF OTHER WINDINGS AVAILABLE, CONSULT FACTORY.

## TERMINATION CHART

### FEEDBACK OPTIONS

(B STANDARD) MS3102R-22-14P			
PIN	Com. Encoder	Resolver	Hall (Note 1)
A	Brake+	Brake+	Brake+
B	Brake-	Brake-	Brake-
C	-	S2 (Sine+)	-
D	-	S4 (Sine-)	-
E	Encoder A	-	-
F	Encoder A	-	-
G	Hall U	S1 (Cosine+)	H1
H	Hall V	S3 (Cosine-)	H2
J	Hall W	-	H3
K	Encoder 5V	R1 (Excit.+)	+5V to +24V
L	Encoder Com	R2 (Excit.-)	Common
M	-	-	-
N	Thermostat	Thermostat	Thermostat
P	Thermostat	Thermostat	Thermostat
R	Encoder B̄	-	-
S	Encoder B	-	-
T	Encoder M	-	-
V	Encoder M̄	-	-

PIN	Modular Encoder	PIN	Modular Encoder
M	5 Volt	S	B
U	Common	R	B̄
F	A	T	M
E	Ā	V	M̄

#### Note 1. Hall Sensor Specifications

Voltage = 5V to 24V  
 Current = 10 ma typical, 25 ma max.  
 Output = Open collector

#### Note 2. Com. Encoder

Current = 250 ma

### MOTOR POWER CONNECTIONS

(B STANDARD) MS3102R-20-4P	
PIN	Motor Winding
A	M1
B	M2
C	M3
D	CASE

## BNR ORDERING INFORMATION – (For Standard Options)

BNR 3 012 A HA B A P A A 000

FRAME SIZE — 3 = 3.38" Dia.

STALL TORQUE — 012 = 12 lb-in  
024 = 24 lb-in  
034 = 34 lb-in

WINDINGS — A = 20 V/Krpm ( $K_T = 1.69$  lb. in./Amp)  
D = 50 V/Krpm ( $K_T = 4.22$  lb. in./Amp)  
E = 60 V/Krpm ( $K_T = 5.07$  lb. in./Amp)

COMMUTATION/FEEDBACK (see note 3)  
 HA = Hall Sensor only  
 MO = Enc. Mtg. Provisions  
 RA = Resolver, 12 Arc Min  
 PA = Resolver, 7 Arc Min  
 SP = Special

Commutating Encoders	Line Count	Modular Encoders*
CB	= 250	= MB
CC	= 500	= MC
CD	= 1000	= MD
CE	= 1024	= ME
CF	= 2500	= MF
SC	= Special	= MS

\*Modular Encoder selection includes Hall Sensor Commutation

BRAKE (Internal) (see note 4)  
 0 = None  
 B = 30 lb-in brake

ENGINEERING MODIFICATIONS  
 SEALING  
 0 = None  
 A = per IP65 w/o shaft seal  
 B = per IP65 w/shaft seal

MOUNTING (see note 1)  
 A = 3.42" Sq. Flange with .500" Dia. x 1.00" long shaft  
 D = NEMA 34 Flange with 0.375" Dia. x 1.19" long shaft  
 M = Metric IEC72 Flange w/12J6 Dia. shaft  
 S = Special Flange and shaft

TERMINATIONS  
 C = Connector, MS3102A-20-4P Motor  
 MS3102A-22-14P Feedback  
 H = Heyco seal-tite w/1.5 ft shielded cable  
 P = Pipe Tap (NPT) w/1.5 ft shielded cable

MATING CONNECTORS (see note 2)  
 0 = None  
 A = Straight  
 B = Rt. Angle  
 S = Special

#### EXAMPLE:

BNR 3 024 A RA B A C A A 000

MODEL/FRAME — 3

24 LB-IN STALL TORQUE — 024

WINDING — A

COMMUTATION — RA

BRAKE — B

ENGINEERING MODIFICATIONS — A

SEALING — A

MOUNTING FEATURES — C

TERMINATIONS — A

MATING CONNECTORS — A

#### Notes:

- Standard BNR3000 motor mounting flanges use NEMA 34 standards but have oversized shaft diameters to carry the rated torque load. Standard NEMA shaft diameters are typically undersized for most servo ratings and are not recommended. Consult CMC regarding acceptable load limits before ordering or applying this option.
- The above motors include standard MS connectors. Connector mates or cables must be ordered separately.
- Standard encoders are dual channel line driver output with a marker pulse and complementary outputs.
- Brakes are for holding static loads and not designed to stop moving loads. Standard coils are 24 volts DC.

## CUSTOMIZE THE 3000 SERIES TO YOUR EXACT REQUIREMENTS

To satisfy various applications with cost-effective solutions, 3000 Series motors are readily available with a wide range of standard capabilities. Final designs are often the result of cooperative efforts between the customer's engineering department and MTI-Torque Systems. For assistance, call your local distributor or Torque Systems direct. We look forward to meeting your custom requirements.

MTH-Torque Systems  
 6 Enterprise Road  
 Billerica, MA 01821  
 Tel: 978.667.5100 or 1.800.669.5112  
 Fax: 978.600.0280

MTI-Torque Systems  
 8201 109th St. Suite 500  
 Pleasant Prairie, WI 53158  
 www.torquesystems.com

sales: customer@slmti.com  
 www.torquesystems.com

